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**these projects, MATLAB is used to reinforce the course material and introduce the students open-ended design problems. The problem of designing an automated steering controller is investigated in three design projects. Initially, the control problem is considered in a simplified form. As the semester age 5.444.1**

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**In order to view a stable response, we will now quickly add the state-feedback control gain  $K$  designed in the Aircraft Pitch: State-Space Methods for Controller Design page. Recall that this gain was designed using the Linear Quadratic Regulator method and resulted in a calculation of  $K = [-0.6435 \ 169.6950 \ 7.0711]$ .**

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### **[LAB2: BLOCK DIAGRAMS AND FEEDBACK](#)**

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**Enter the following command in MATLAB. You should see the following plot which is equivalent to the Scope's output. `step(num,den)`; Implementing full state-feedback control. In the Suspension: State-Space Controller Design page a full state-feedback controller was designed feeding back the following five states: (1)**

### [Optimal control - Wikipedia](#)

**feedback control did not fit the pedagogy were the genesis of this textbook. Therefore, this textbook is unique in several ways. Most importantly, it is focused, in its organization, in its examples, and in its homework problems, on a particular, but fairly general, end-to-end design strategy and methodology.**

**Topics**

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